Contextual Dependent Click Bandit Algorithm for Web Recommendation

COCOON 2018

Weiwen Liu¹, Shuai Li¹, and Shengyu Zhang^{1,2}

¹The Chinese University of Hong Kong, Hong Kong ²Tencent, Shenzhen, China Given a search query, a web page recommendation algorithm recommends Goog

a list of related web pages.

- In the online scenario, the learning agent
 - receives user feedback and makes predictions according to previous user behaviors.
 - aims at maintaining a high Click-Through Rate (CTR) over a long period of time

learr	ning to ran	ik				Ŷ	٩
AI	Videos	Shopping	Images	News	More	Settings T	ool
Abou	t 186,000,00	0 results (0.41	seconds)				
rank supe cons	ing (MLR) ervised, se		ation of m d or reinfo	achine le	arning, typical learning, in th	e man	11
Lear	rning to r :://en.wikipe	ank - Wikip adia.org/wiki/L	edia .earning_to_	rank	Ø ^	opersourcemention	
https Learn learni mode	:,//en.wikipe ning to rank. ing, typically sis for inform		earning_to_ k or machine mi-supervise systems.	elearned ra d or reinford	cement learning,	e application of machine in the construction of rank	ing
https May 3	:://towardsd 3, 2017 - To I	latascience.co	m/learning g model we	to-rank-wit need some		ata Science earn-327a5cfd81f + . So let's generate some	
https Aug 5	c//www.quo 5, 2017 - Ran	vra.com/What- kNet, LambdaR	is-the-intuiti ank and Larr	ve-explana ibdaMART (ire all what we ca	nd to Rank-and-algo I Learning to Rank revised machine learning	

How do companies get training data for implementing ... 1 answer Mar 27, 2017 What are the differences between pointwise, pairwise ... 2 answers Sep 27, 2016 To use a learning to rank algorithm, how do I have to ... 1 answer Mar 18, 2015

(ML) to solve ranking problems

- Online recommendation involves a fundamental choice:
 - **Exploitation:** exploiting the currently confirmed attractive yet suboptimal items
 - **Exploration:** exploring uncertain but potentially interesting items which may produce large benefits later
- The best long-term strategy may involve short-term sacrifices
- We need to gather enough information to make the best overall decisions

Multi-armed Bandit

- At each round t, the learning agent selects one arm i_t , and receives a reward $R_t(i_t)$.
- Cumulative regret after *n* rounds is

$$\mathsf{regret} = n\mu^* - \mathbb{E}[\sum_{t=1}^n R_t(i_t)].$$

• The objective is to minimize the cumulative regret.

Upper Confidence Bound (UCB) Algorithm

• Estimate the mean reward $\hat{Q}_t(a)$ of $Q_t(a)$, and the confidence radius $\hat{U}_t(a)$ for each arm *a*, such that Q(a) is upper bounded by

 $Q(a) \leq \hat{Q}_t(a) + \hat{U}_t(a)$

with high probability.

• The estimation depends on the number of times N(a) that item a has been selected.

Small $N_t(a)$: large $\hat{U}_t(a)$ (estimation more uncertain) **Large** $N_t(a)$: small $\hat{U}_t(a)$ (estimation more accurate)

• UCB algorithm: Select an arm that maximizes the Upper Confidence Bound (UCB)

$$a_t = \arg \max_{a} \underbrace{\hat{Q}_t(a)}_{\text{Exploitation}} + \underbrace{\hat{U}_t(a)}_{\text{Exploration}}.$$

- Action is combinatorial \Rightarrow generate a ranked list at each time step.
- Semi-bandit feedback ⇒ only outcomes of the played arms are observed to the agent.
- Challenges
 - Exponential number of actions \Rightarrow cannot be fully explored.

- A lot of available features:
 - user profiles, search keywords, hyperlinks, images, tags, comments, titles, etc.
- A solution to the cold-start problem in the recommender systems

Dependent Click Model (DCM)

- models multiple clicks.
- Two sets of unknown parameters to be estimated:
 - attraction probability: item-dependent parameters
 - termination probability: position-dependent parameters

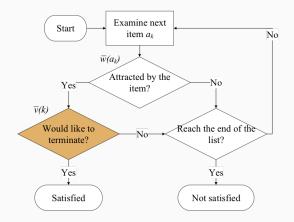


Figure 1: Dependent click model

• A set of ground items $E = \{1, ..., L\}$ and a feasible action set $\Pi_{\mathcal{K}}(E)$.

- A set of ground items $E = \{1, ..., L\}$ and a feasible action set $\Pi_{\mathcal{K}}(E)$.
- At each time step t,
 - A set of contextual vectors is given {x_{i,t}}_{i∈E} (e.g., user profiles/ keywords).

- A set of ground items $E = \{1, ..., L\}$ and a feasible action set $\Pi_{\mathcal{K}}(E)$.
- At each time step t,
 - A set of contextual vectors is given {x_{i,t}}_{i∈E} (e.g., user profiles/ keywords).
 - The learning agent selects an ordered list A_t = (a^t₁,...,a^t_K) of K distinct items

- A set of ground items $E = \{1, ..., L\}$ and a feasible action set $\Pi_{\mathcal{K}}(E)$.
- At each time step t,
 - A set of contextual vectors is given {x_{i,t}}_{i∈E} (e.g., user profiles/ keywords).
 - The learning agent selects an ordered list A_t = (a^t₁,...,a^t_K) of K distinct items
 - The user checks the list of items one by one from top to bottom. For each item a at position k,
 - the user is **attracted** with probability $\bar{w}_t(a) \in [0, 1]$.
 - if attracted (the user clicks the item), the user will feel satisfied and leave with probability v
 _t(k).

- A set of ground items $E = \{1, ..., L\}$ and a feasible action set $\Pi_{\mathcal{K}}(E)$.
- At each time step t,
 - A set of contextual vectors is given {x_{i,t}}_{i∈E} (e.g., user profiles/ keywords).
 - The learning agent selects an ordered list A_t = (a^t₁,...,a^t_K) of K distinct items
 - The user checks the list of items one by one from top to bottom. For each item a at position k,
 - the user is **attracted** with probability $\bar{w}_t(a) \in [0, 1]$.
 - if attracted (the user clicks the item), the user will feel satisfied and leave with probability v
 _t(k).
 - The feedback is a sequence of k binary click indicators $(\mathbf{w}'_1, \ldots, \mathbf{w}'_K)$.

• The reward of action A is defined by

$$f(A, v, w) = 1 - \prod_{k=1}^{K} (1 - v(k)w(a_k)).$$

• The reward of action A is defined by

$$f(A, v, w) = 1 - \prod_{k=1}^{K} (1 - v(k)w(a_k)).$$

• The cumulative regret in *n* rounds

$$\mathcal{R}(n) = \mathbb{E}\Big[\sum_{t=1}^{n} \big(f(A_t^*, \bar{v}_t, \bar{w}_t) - f(\mathbf{A}_t, \bar{v}_t, \bar{w}_t)\big)\Big],$$

where A_t^* is the optimal list.

• The reward is not revealed to the learning agent since the leaving position is ambiguous, e.g.,

 $0100110000 \Rightarrow \begin{cases} \text{leave at the 6-th item with satisfaction,} \\ \text{finish the list and find nothing satisfied.} \end{cases}$

 The attraction weight w_t(a) satisfies the generalized linear model (GLM)

$$\bar{w}_t(a) = \mathbb{E}[\mathbf{w}_t(a)|\mathcal{H}_t] = \mu(\theta_*^\top x_{t,a}),$$

where

- $\{\mathcal{H}_t\}_{t=1}^n$ represents the history up to time t,
- $heta_*$ is a fixed but unknown vector $heta_* \in \mathbb{R}^d$
- The inverse link function μ is chosen s.t. $0 \le \mu(\theta^+_* x_{t,a}) \le 1$. This GLM admits a wider range of nonlinear distributions such as Gaussian, binomial, Poisson, gamma distributions, etc. In particular, when the feedback is binary or count variables, the logistic or Poisson regression can be used.

¹Sumeet Katariya et al. "DCM bandits: Learning to rank with multiple clicks". In: *International Conference on Machine Learning*. 2016, pp. 1215–1224.

 The attraction weight w_t(a) satisfies the generalized linear model (GLM)

$$\bar{w}_t(a) = \mathbb{E}[\mathbf{w}_t(a)|\mathcal{H}_t] = \mu(\theta_*^\top x_{t,a}),$$

where

- $\{\mathcal{H}_t\}_{t=1}^n$ represents the history up to time t,
- $heta_*$ is a fixed but unknown vector $heta_* \in \mathbb{R}^d$
- The inverse link function μ is chosen s.t. $0 \le \mu(\theta_*^\top x_{t,a}) \le 1$. This GLM admits a wider range of nonlinear distributions such as Gaussian, binomial, Poisson, gamma distributions, etc. In particular, when the feedback is binary or count variables, the logistic or Poisson regression can be used.
- we adopt the same assumption as in [Katariya et al., 2016]¹ that the order π(ν̄) of ν̄ = (ν̄(1),..., ν̄(K)) is known to the agent.

¹Sumeet Katariya et al. "DCM bandits: Learning to rank with multiple clicks". In: *International Conference on Machine Learning*. 2016, pp. 1215–1224.

- For round $t = 1, \ldots, n$
 - Obtain context $x_{t,a}$ for all $a \in E$.

- For round $t = 1, \ldots, n$
 - Obtain context $x_{t,a}$ for all $a \in E$.
 - By w_t(a) = μ(θ^T_{*}×_{t,a}), we obtain an estimate θ̂_{t-1} of θ_{*}, solved by Maximum Likelihood Estimation (MLE). With high probability,

$$\mathbf{w}_t(a) \in \left[\mu(\hat{\theta}_{t-1}^\top x_{t,a}) - \rho(t-1) \| x_{t,a} \|_{\mathbf{V}_{t-1}^{-1}}, \mu(\hat{\theta}_{t-1}^\top x_{t,a}) + \rho(t-1) \| x_{t,a} \|_{\mathbf{V}_{t-1}^{-1}} \right]$$

- For round $t = 1, \ldots, n$
 - Obtain context $x_{t,a}$ for all $a \in E$.
 - By w_t(a) = μ(θ^T_{*}×_{t,a}), we obtain an estimate θ̂_{t-1} of θ_{*}, solved by Maximum Likelihood Estimation (MLE). With high probability,

$$\mathbf{w}_t(\mathbf{a}) \in \left[\mu(\hat{\theta}_{t-1}^\top x_{t,s}) - \rho(t-1) \| x_{t,s} \|_{\mathbf{V}_{t-1}^{-1}}, \mu(\hat{\theta}_{t-1}^\top x_{t,s}) + \rho(t-1) \| x_{t,s} \|_{\mathbf{V}_{t-1}^{-1}} \right]$$

• Compute the Upper Confidence Bound (UCB) of each arm $a \in E$,

$$\mathbf{U}_{t}(a) = \min\{\mu(\hat{\theta}_{t-1}^{\top} x_{t,a}) + \rho(t-1) \| x_{t,a} \|_{\mathbf{V}_{t-1}^{-1}}, 1\}.$$

- For round $t = 1, \ldots, n$
 - Obtain context $x_{t,a}$ for all $a \in E$.
 - By w_t(a) = μ(θ^T_{*} x_{t,a}), we obtain an estimate θ̂_{t-1} of θ_{*}, solved by Maximum Likelihood Estimation (MLE). With high probability,

$$\mathbf{w}_{t}(a) \in \left[\mu(\hat{\theta}_{t-1}^{\top} x_{t,a}) - \rho(t-1) \|x_{t,a}\|_{\mathbf{V}_{t-1}^{-1}}, \mu(\hat{\theta}_{t-1}^{\top} x_{t,a}) + \rho(t-1) \|x_{t,a}\|_{\mathbf{V}_{t-1}^{-1}}\right]$$

- Compute the Upper Confidence Bound (UCB) of each arm $a \in E$, $U_t(a) = \min\{\mu(\hat{\theta}_{t-1}^\top x_{t,a}) + \rho(t-1) \|x_{t,a}\|_{\mathbf{V}^{-1}}, 1\}.$
- Select action

$$\mathbf{A}_t \leftarrow \operatorname{argmax}_{A \in \Pi_K(E)} f(A, \bar{v}_t, \mathbf{U}_t).$$

- For round $t = 1, \ldots, n$
 - Obtain context $x_{t,a}$ for all $a \in E$.
 - By w_t(a) = μ(θ^T_{*} x_{t,a}), we obtain an estimate θ̂_{t-1} of θ_{*}, solved by Maximum Likelihood Estimation (MLE). With high probability,

$$\mathbf{w}_{t}(a) \in \left[\mu(\hat{\theta}_{t-1}^{\top} x_{t,a}) - \rho(t-1) \|x_{t,a}\|_{\mathbf{V}_{t-1}^{-1}}, \mu(\hat{\theta}_{t-1}^{\top} x_{t,a}) + \rho(t-1) \|x_{t,a}\|_{\mathbf{V}_{t-1}^{-1}}\right]$$

- Compute the Upper Confidence Bound (UCB) of each arm $a \in E$, $U_t(a) = \min\{\mu(\hat{\theta}_{t-1}^\top x_{t,a}) + \rho(t-1) \|x_{t,a}\|_{\mathbf{V}^{-1}}, 1\}.$
- Select action

$$\mathbf{A}_t \leftarrow \operatorname{argmax}_{A \in \Pi_{\mathcal{K}}(E)} f(A, \bar{v}_t, \mathbf{U}_t).$$

Play A_t and observe the last click position C_t, and the click sequence w_t(a^t_k), k ∈ [C_t].

- For round $t = 1, \ldots, n$
 - Obtain context $x_{t,a}$ for all $a \in E$.
 - By w_t(a) = μ(θ^T_{*} x_{t,a}), we obtain an estimate θ̂_{t-1} of θ_{*}, solved by Maximum Likelihood Estimation (MLE). With high probability,

$$\mathbf{w}_{t}(a) \in \left[\mu(\hat{\theta}_{t-1}^{\top} x_{t,a}) - \rho(t-1) \|x_{t,a}\|_{\mathbf{V}_{t-1}^{-1}}, \mu(\hat{\theta}_{t-1}^{\top} x_{t,a}) + \rho(t-1) \|x_{t,a}\|_{\mathbf{V}_{t-1}^{-1}}\right]$$

- Compute the Upper Confidence Bound (UCB) of each arm $a \in E$, $U_t(a) = \min\{\mu(\hat{\theta}_{t-1}^\top x_{t,a}) + \rho(t-1) \|x_{t,a}\|_{\mathbf{V}^{-1}}, 1\}.$
- Select action

$$\mathbf{A}_t \leftarrow \operatorname{argmax}_{A \in \Pi_K(E)} f(A, \bar{v}_t, \mathbf{U}_t).$$

- Play A_t and observe the last click position C_t, and the click sequence w_t(a^t_k), k ∈ [C_t].
- Update $\mathbf{V}_t \leftarrow \mathbf{V}_{t-1} + \sum_{k=1}^{C_t} x_{t,\mathbf{a}_k^t} \mathbf{x}_{t,\mathbf{a}_k^t}^{\top}$

Lemma [Li et al., 2017]²

For any $\delta \in [1/n,1)$, with probability at least $1-\delta$, for all $1 \leq t \leq n$, we have

$$\|\hat{ heta}_t - heta_*\|_{\mathbf{V}_t} \leq rac{\sigma}{c_\mu} \sqrt{rac{d}{2} \log(1 + t/(\lambda d))} + \log(1/\delta)$$

²Lihong Li, Yu Lu, and Dengyong Zhou. "Provable Optimal Algorithms for Generalized Linear Contextual Bandits". In: *Proceedings of The 34rd International Conference on Machine Learning* (2017).

Result

Theorem

For $n \ge 1$, and the reward function $f(A, v, w) = 1 - \prod_{k=1}^{K} (1 - v(k)w(a_k))$, the cumulative regret $\mathcal{R}(n)$ has a bound of $O(d\sqrt{n})$

$$\mathcal{R}(n) \leq rac{4d\mathcal{K}p_{v}k_{\mu}\sigma}{c_{\mu}}\sqrt{n\mathcal{K}\log\left(rac{1+n/(\lambda d)}{\delta}
ight)\log(1+\mathcal{K}n/(\lambda d))}$$

- independent of the size of the ground item set *L*.
- improves the previous regret bound in [Filippi et al., 2010]³ by a $\sqrt{\log(n)}$ term.

³Sarah Filippi et al. "Parametric bandits: The generalized linear case". In: Advances in Neural Information Processing Systems. 2010, pp. 586–594.

• Reduce the problem to the cascading bandit problem

$$\mathbb{E}[\mathcal{R}_t | \mathcal{H}_t] = f(A_t^*, \bar{v}_t, \bar{w}_t) - f(\mathbf{A}_t, \bar{v}_t, \bar{w}_t)$$

$$\leq \sum_{k=1}^{K} \bar{v}_t(k) \bar{w}_t(a_k^*) - \sum_{k=1}^{K} \bar{v}_t(k) \bar{w}_t(\mathbf{a}_k^t)$$
(by definition of A_t^* and f)
$$= \sum_{i=1}^{K} (\bar{v}_t(i) - \bar{v}_t(i+1)) \sum_{k=1}^{i} (\bar{w}_t(a_k^*) - \bar{w}_t(\mathbf{a}_k^t)),$$

where $\bar{v}_t(K+1) = 0$.

• Use the following Lemma to bound the cascade difference,

Lemma

Let $t \ge 1$ and $\mathbf{A}_t = (\mathbf{a}_1^t, ..., \mathbf{a}_i^t)$, $i \in [K]$, we have:

$$\sum_{k=1}^{i} (\mu(\theta_*^{\top} x_{t,a_k^*}) - \mu(\theta_*^{\top} x_{t,a_k^t})) \le 2 \sum_{k=1}^{i} \rho(t-1) \|x_{t,a_k^t}\|_{\mathbf{V}_{t-1}^{-1}},$$

where $ho(t) = rac{k_\mu\sigma}{c_\mu}\sqrt{rac{d}{2}\log(1+t/(\lambda d))} + \log(1/\delta).$

• The norm term can be further bounded by

Lemma

If $\lambda \geq K$, then

$$\sum_{s=1}^{t} \sum_{k=1}^{i} \left\| x_{s,\mathbf{a}_{k}^{s}} \right\|_{V_{t}^{-1}}^{2} \leq 2d \log(1 + \frac{Kt}{\lambda d}).$$

Experiment: Synthetic Data

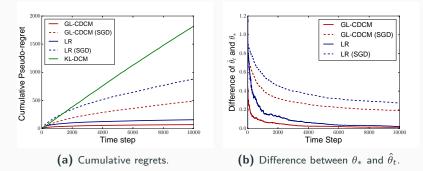
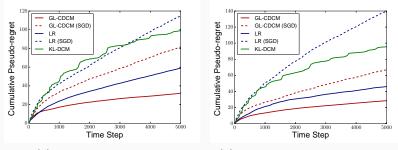
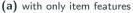


Figure 2: Synthetic data, select K = 5 items out of L = 200 items, dimension d = 100.

Experiment: Real-world Data





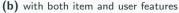


Figure 3: Yandex Dataset: select K = 10 items out of L = 100 items, dimension d = 200.

- Present a bandit algorithm for web page recommendation that automatically balances the exploration and exploitation.
- Incorporate contextual information in DCM bandit.
- Prove a regret bound of $\tilde{O}(d\sqrt{n})$ for the algorithm.